The traveling salesman problem with few inner points

Yoshio Okamoto* (Joint work with Michael Hoffmann) Mittagsseminar, April 6, 2004

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Given: finite set of points on \mathbb{R}^2 Find: a minimum-length tour

The 2DTSP

Given: finite set of points on ${\rm I\!R}^2$ Find: a minimum-length tour





 In general, it is NP-hard. (Garey, Graham & Johnson '76 Papadimitriou '77)
 When the points are in convex position, the problem is easy.









Observation

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The **inner points** make the problem difficult.





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Motivation

How many inner points can we have in order to obtain a polynomial-time algorithm?



We give two simple algorithms.

- n := the total number of points
- k := the number of inner points
- First algorithm runs in polynomial time when k = O(1).
- ♦ Second algorithm runs in polynomial time when $k = O(\log n / \log \log n)$.



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Corollary



An optimal tour visits the non-inner points in a cyclic order.





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Suppose not. Then ∃ a "skip." Skipped points must be visited later, which causes a selfcrossing. A contradiction.

One inner point

Consider the case k = 1. (k := # of inner pts)

Inner point: qNon-inner points: p_1, p_2, \dots, p_{n-1} labeled according to a cyclic order



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One inner point

of tours which "respect" the cycl. order = n-1.



Choose the best one.

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- (2) Fix a cyclic order on the non-inner points;
- (3) For each tour which respects the cyclic order

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There are k inner points.

- # of tours which "respect" the cycl. order = $O(k!n^k)$.
- They can be enumerated in O(1) time per tour.
- The length of each tour can be computed in O(n) time.

The running time =
$$O(n \log n) + O(k!n^{k+1})$$
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convex hull computation

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Another fact

An optimal tour respects some linear order on the inner points.





- (2) Fix a cyclic order on the non-inner points;
- (3) For each linear order on the inner points
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Optimal tour among those which respect the cyclic order and the order "1-2-3."



Optimal tour among those which respect the cyclic order and the order "1-3-2."



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- Not yet clear: How to do Step (3i)??

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Dynamic programming

a cycl. order on the non-inner pts p_1,\ldots,p_{n-k} a linear order on the inner pts q_1,\ldots,q_k F(i, j) := the length of a shortest path from p_1 to p_i via p_1, \ldots, p_i and q_1, \ldots, q_j which respects these two orders **q**₁ **q**₂ p_1 \mathfrak{p}_5 p_2 p_3 \mathfrak{p}_4 (i = 5, j = 2)

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Main recurrence

It holds that

$\begin{array}{lll} F(\underline{i+1},j) &=& \mbox{minimum of} \\ && F(\underline{i},j) + d(p_i,p_{i+1}) \mbox{ and} \\ && F(i,\underline{j}) + d(q_j,p_{i+1}). \end{array}$



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♦ By the dynamic programming technique, F(<u>n-k</u>, k) and F(n-k, <u>k</u>) can be computed in O(kn) time.

♦ The length of a shortest tour which respects these two orders is the minimum of $F(\underline{n-k}, k) + d(p_{n-k}, p_1)$ and $F(\underline{n-k}, \underline{k}) + d(q_k, p_1)$.



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What remains: the analysis of the running time

Running time

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When $k = O(\log n / \log \log n)$, this is poly. in n.$

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The same strategy works for other problems.

The prize-collecting TSP The partial TSP



The 2D versions of these problems with k inner points can be solved in polynomial time when $k = O(\log n / \log \log n)$.



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 - bounded treewidth
 - bounded genus

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- Geometric optimization problems in 2D
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Geometric optimization problems in 2D
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