

# The affine representation theorem for abstract convex geometries

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## Combinatorial abstract models of geometric concepts

◆ **Matroids** ..... abstraction of dependence

Application: {  
Finite geometry  
Coding theory  
Combinatorial optimization

◆ **Oriented Matroids** ..... abstraction of dependence

Application: {  
Convex polytopes  
Computational geometry  
Discrete geometry  
Optimization

◆ **Convex geometries** ..... abstraction of convexity

Application: {  
Discrete geometry  
Social choice theory  
Mathematical psychology

◆ **Matroids** ..... abstraction of dependence

Every matroid can be represented  
as a homotopy-sphere arrangement.  
(Swartz, '03)

◆ **Oriented Matroids** ..... abstraction of dependence

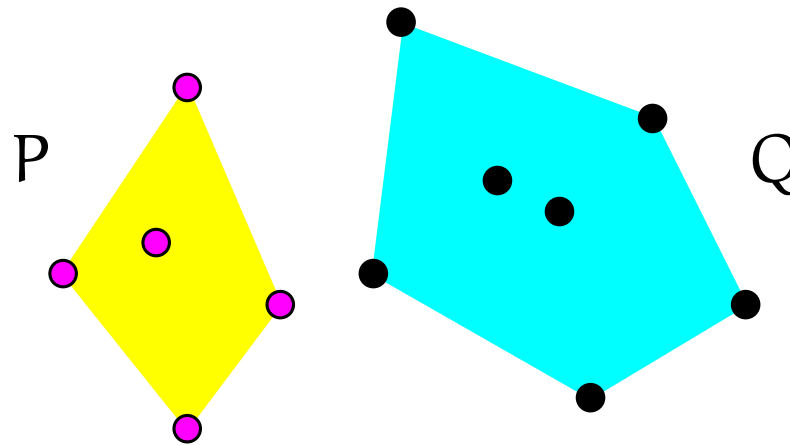
Every oriented matroid can be represented  
as a pseudohyperplane arrangement.  
(Forkman–Lawrence, '78)

◆ **Convex geometries** ..... abstraction of convexity

??????????

**Our Theorem:**

Every convex geometry is isomorphic to some **generalized convex shelling**,



determined by two point sets  $P$  and  $Q$  satisfying that  $\text{conv}(P) \cap \text{conv}(Q) = \emptyset$ .

This gives an **affine representation** of a convex geometry.

## Our Theorem:

Every convex geometry is isomorphic to some **generalized convex shelling**.

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In the rest of my talk

- ◆ Definition of a convex geometry
- ◆ Examples of a convex geometry
- ◆ Definition of a generalized convex shelling
- ◆ Our theorem
- ◆ Outline of the proof

(Edelman–Jamison '85)

$E$  a nonempty finite set

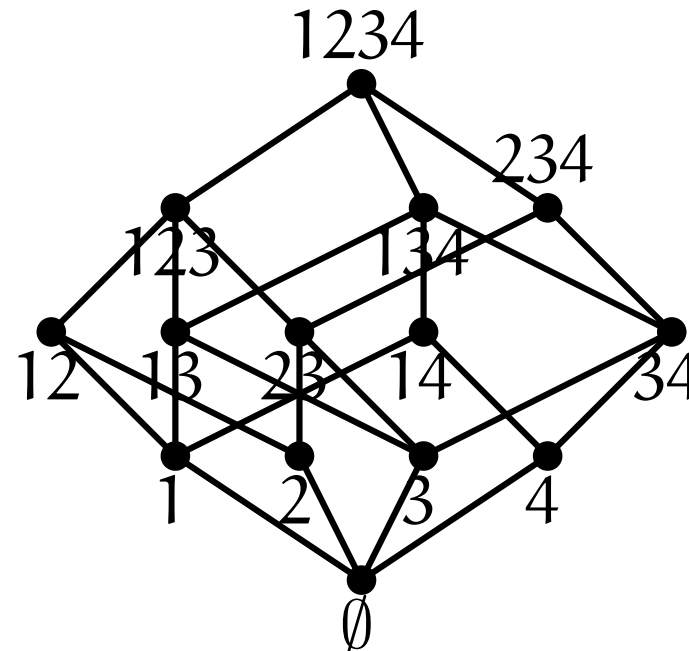
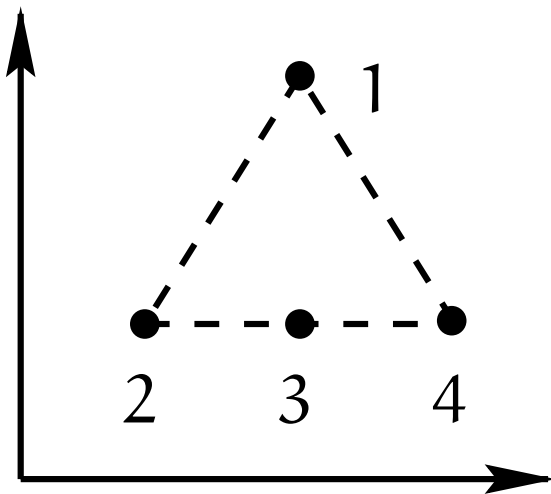
$\mathcal{L}$  a nonempty family of subsets of  $E$

**Def.**  $\mathcal{L} \subseteq 2^E$  is called a **convex geometry** on  $E$   
if  $\mathcal{L}$  satisfies the following three conditions.

- (1)  $\emptyset \in \mathcal{L}, E \in \mathcal{L}$ .
- (2)  $X, Y \in \mathcal{L} \implies X \cap Y \in \mathcal{L}$ .
- (3)  $X \in \mathcal{L} \setminus \{E\} \implies \exists e \in E \setminus X$  s.t.  $X \cup \{e\} \in \mathcal{L}$ .

$Q$  a finite point set in  $\mathbb{R}^d$

Define:  $\mathcal{L} = \{X \subseteq Q : \text{conv}(X) \cap (Q \setminus X) = \emptyset\}$ .



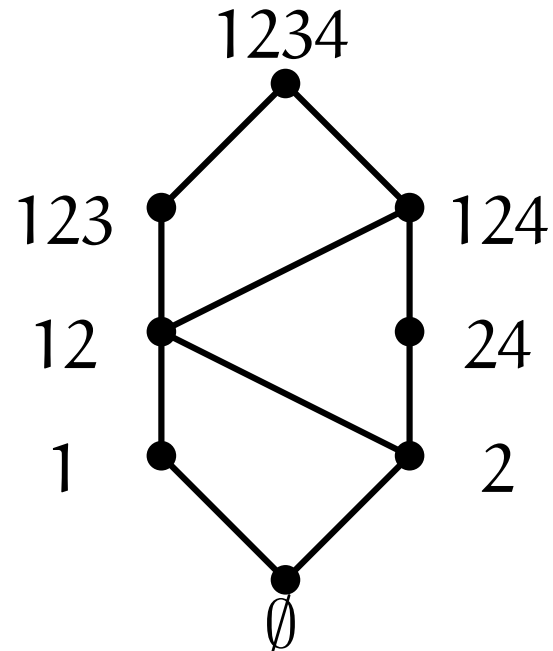
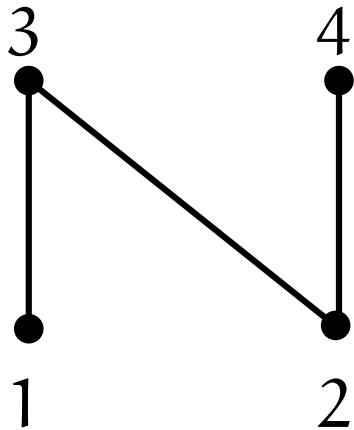
$\mathcal{L}$  is a convex geometry and called the convex shelling on  $Q$ .



## Example 2: poset shelling

$\mathcal{P} = (E, \leq)$  a partially ordered set

Define:  $\mathcal{L} = \{X \subseteq E : e \in X, f \leq e \Rightarrow f \in X\}$ .



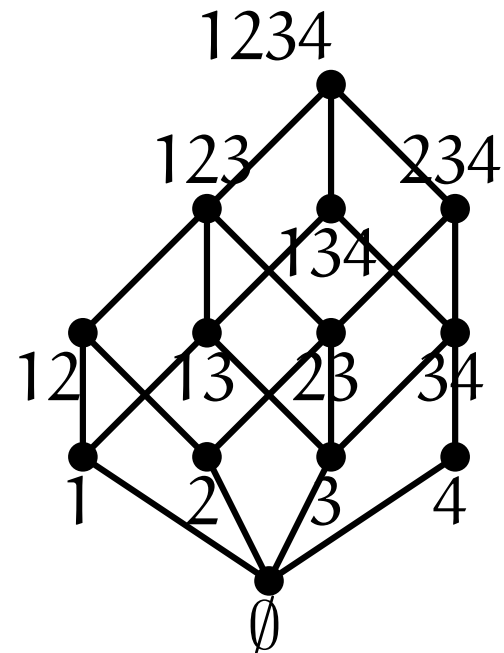
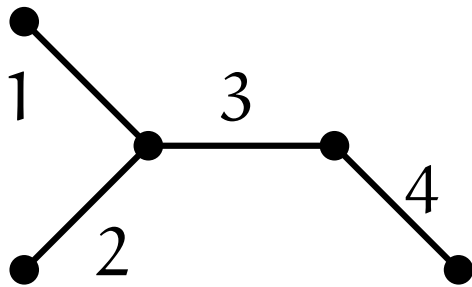
$\mathcal{L}$  is a convex geometry on  $E$  and called the poset shelling of  $\mathcal{P}$ .



$T = (V, E)$  a tree

Define:

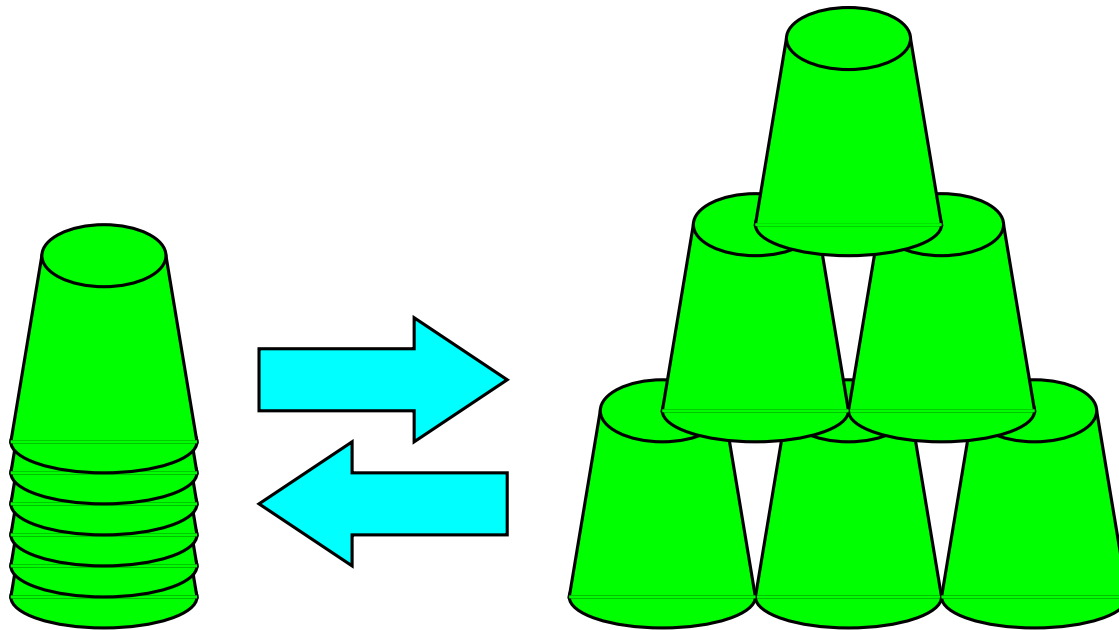
$$\mathcal{L} = \{X \subseteq E : X \text{ forms a subtree of } T\}.$$



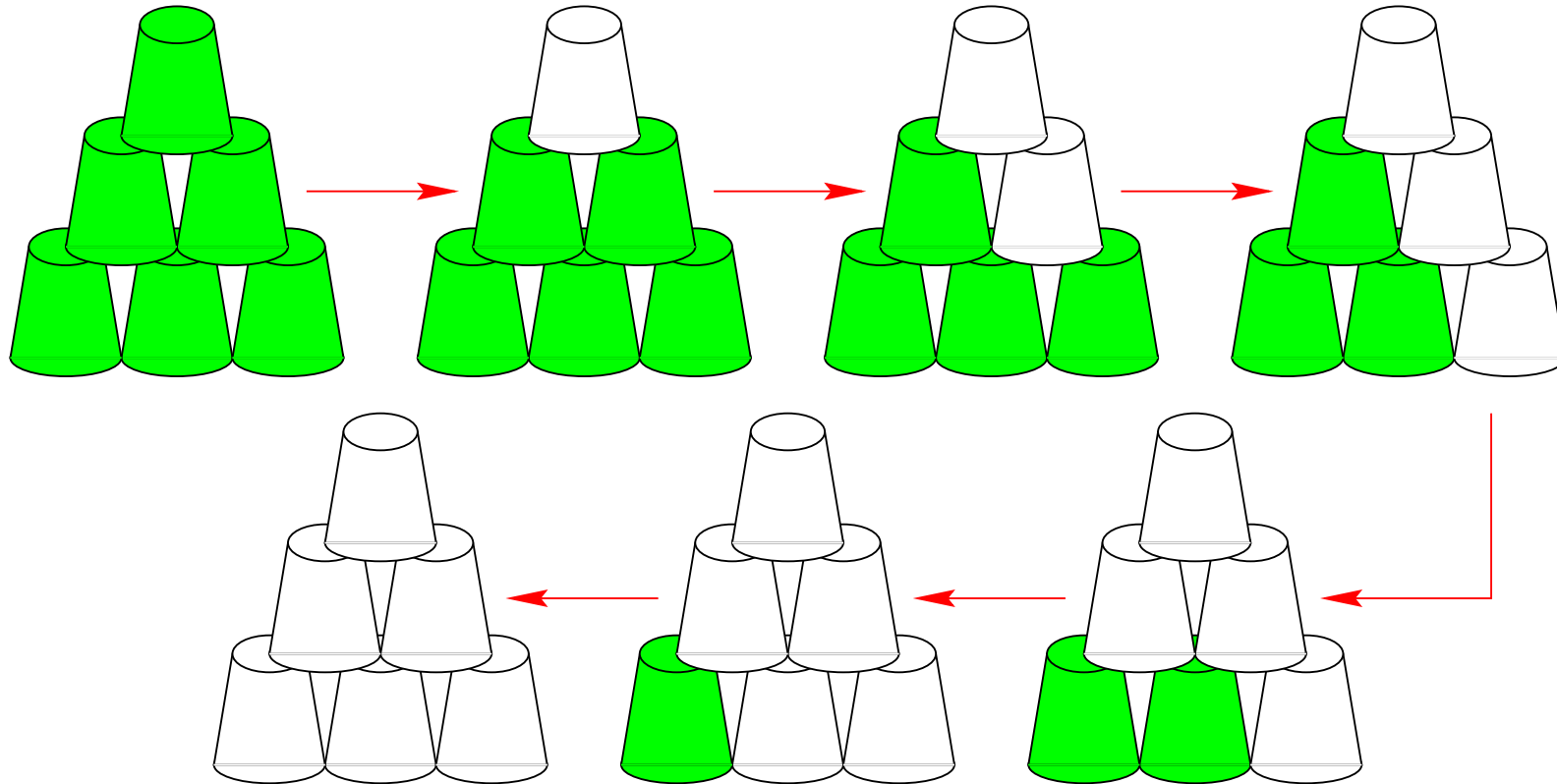
$\mathcal{L}$  is a convex geometry on  $E$  and called the tree shelling of  $T$

## What is “cupstacks”?

Construct the tower from the pile and get it back as quickly as possible.

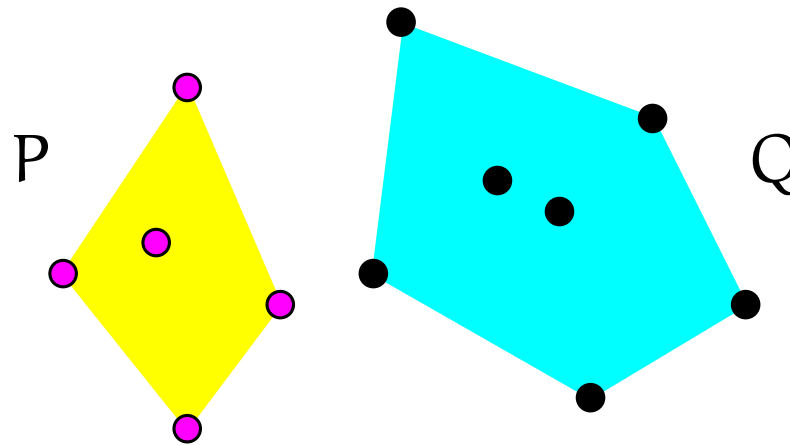


A sequence in collapsing



**Our Theorem:**

Every convex geometry is isomorphic to some **generalized convex shelling**,

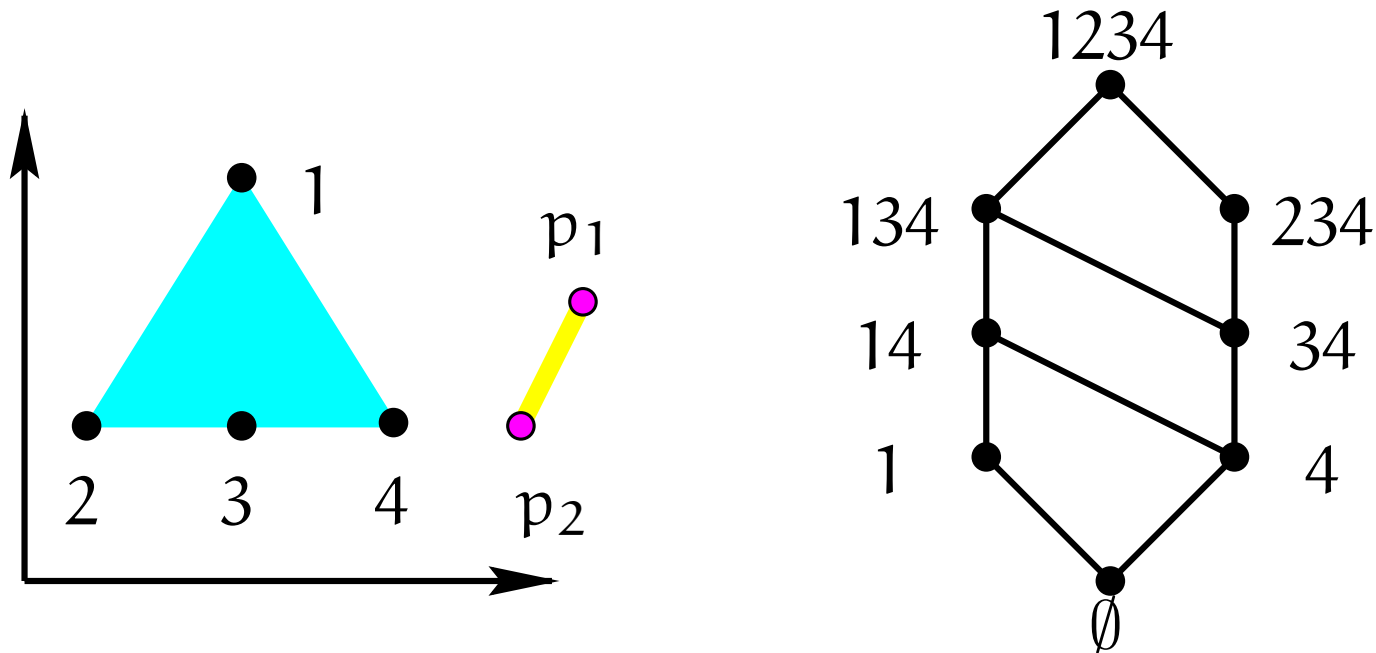


determined by two point sets P and Q  
satisfying that  $\text{conv}(P) \cap \text{conv}(Q) = \emptyset$ .

This gives an **affine representation** of a convex geometry.

$P, Q$  finite point sets in  $\mathbb{R}^d$  satisfying  $\text{conv}(P) \cap Q = \emptyset$

Define:  $\mathcal{L} = \{X \subseteq Q : \text{conv}(X \cup P) \cap (Q \setminus X) = \emptyset\}$ .



$\mathcal{L}$  is a convex geometry on  $Q$  and called  
the generalized convex shelling on  $Q$  with respect to  $P$ .

**Our Theorem**

Every convex geometry is isomorphic to some generalized convex shelling.

In other words,

For any convex geometry  $\mathcal{L}$ , there exist finite point sets  $P$  and  $Q$  such that  $\mathcal{L}$  is isomorphic to the generalized convex shelling on  $Q$  w.r.t.  $P$ .

Convex geometries = Generalized convex shellings

Tree shellings

Poset shellings

Convex shellings

◆ For oriented matroids and matroids, we have

Topological representation theorems.

◆ For convex geometries, we have

Affine representation theorem.

⇒ An intrinsic simplicity of convex geometries



The proof goes along the following line.

We are given a convex geometry  $\mathcal{L}$ .

(1) **Construct:**

point sets  $P$  and  $Q$  from  $\mathcal{L}$ .

(2) **Show:**

$\mathcal{L} \cong$  the generalized convex shelling on  $Q$  w.r.t.  $P$ .

To illustrate the proof, we will show a much weaker version.

What we will show

For any poset shelling  $\mathcal{L}$   
there exist point sets  $P$  and  $Q$  such that  
 $\mathcal{L}$  is isomorphic to  
the generalized convex shelling on  $Q$  w.r.t.  $P$ .

Given a partially ordered set  $\mathcal{P} = (E, \leq)$ . Let  $n := |E|$ .

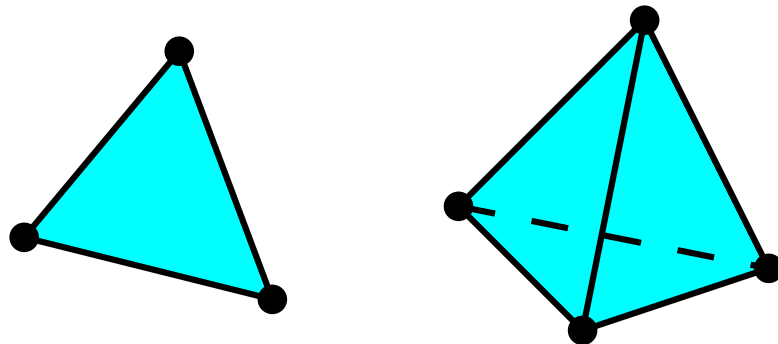
### Construction of $Q$

We use the  $(n - 1)$ -dimensional space  $\mathbb{R}^{n-1}$ .

For each  $e \in E$ , put a point  $\mathbf{q}(e)$  such that

$\{\mathbf{q}(e) : e \in E\}$  is affinely independent,

( $\text{conv}(\{\mathbf{q}(e) : e \in E\})$  is an  $(n - 1)$ -simplex).



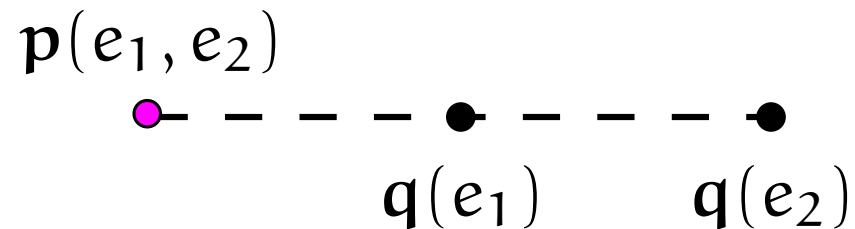
Let  $Q = \{\mathbf{q}(e) : e \in E\}$ .

Given a partially ordered set  $\mathcal{P} = (E, \leq)$ . Let  $n := |E|$ .

### Construction of $P$

For each  $e_1, e_2 \in E$  such that  $e_1 < e_2$ ,

Put a point  $\mathbf{p}(e_1, e_2)$  such that  $\mathbf{q}(e_1) = \frac{\mathbf{p}(e_1, e_2) + \mathbf{q}(e_2)}{2}$ .



Let  $P = \{\mathbf{p}(e_1, e_2) : e_1, e_2 \in E, e_1 < e_2\}$ .

**Claim** the poset shelling of  $\mathcal{P} = (E, \leq)$   
 $\cong$  the generalized convex shelling on  $Q$  w.r.t.  $P$ .

**Proof sketch.**

(1) When is  $e \in E$  allowed to be removed?

$e$  is allowed to be removed  $\iff$  all  $f$ 's such that  $e < f$  have been already removed.

(2) When is  $q(e) \in Q$  allowed to be removed?

$q(e)$  is allowed to be removed  $\iff$  all  $q(f)$ 's s.t.  $p(e, f) \in P$  have been already removed.

(3)  $e < f \iff p(e, f) \in P$ .

What was our theorem??

## Our Theorem

Every convex geometry is isomorphic to some generalized convex shelling.

This theorem is expected to be useful for a lot of problems in convex geometries.

⇒ Opens a new research direction!

Based on our theorem...

◆ Hachimori & Nakamura

- Consider a certain clutter associated with a convex geometry
- Characterized the 2-dim. generalized convex shellings with MFMC clutters.

◆ Okamoto

- Study the local topology of a certain simplicial complex associated with a convex geometry (conjectured by Edelman & Reiner '00)
- Solved the conjecture for 2-dim. generalized convex shellings.